Rapid Development of Aerodynamic Models for UCAV Flight Dynamics & Control Studies

Dr Doug Greenwell

Department of Aerospace Engineering
University of Bristol



maintaining the data needed, and c including suggestions for reducing	lection of information is estimated to ompleting and reviewing the collect this burden, to Washington Headqu uld be aware that notwithstanding ar DMB control number.	ion of information. Send comments arters Services, Directorate for Information	regarding this burden estimate or mation Operations and Reports	or any other aspect of th , 1215 Jefferson Davis l	is collection of information, Highway, Suite 1204, Arlington	
1. REPORT DATE 26 JUL 2004		2. REPORT TYPE N/A		3. DATES COVERED		
4. TITLE AND SUBTITLE				5a. CONTRACT NUMBER		
Rapid Development of Aerodynamic Models for UCAV Flight Dynamics & Control Studies				5b. GRANT NUMBER		
& Control Studies				5c. PROGRAM ELEMENT NUMBER		
6. AUTHOR(S)				5d. PROJECT NUMBER		
				5e. TASK NUMBER		
				5f. WORK UNIT NUMBER		
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) Department of Aerospace Engineering University of Bristol				8. PERFORMING ORGANIZATION REPORT NUMBER		
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)				10. SPONSOR/MONITOR'S ACRONYM(S)		
				11. SPONSOR/MONITOR'S REPORT NUMBER(S)		
12. DISTRIBUTION/AVAILABILITY STATEMENT Approved for public release, distribution unlimited						
	otes 85, CSP 02-5078, Pr al document contain	_	lynamic Issues of	Unmanned A	Air Vehicles	
14. ABSTRACT						
15. SUBJECT TERMS						
16. SECURITY CLASSIFIC	17. LIMITATION OF	18. NUMBER	19a. NAME OF			
a. REPORT unclassified	b. ABSTRACT unclassified	c. THIS PAGE unclassified	- ABSTRACT UU	OF PAGES 9	RESPONSIBLE PERSON	

Report Documentation Page

Form Approved OMB No. 0704-0188

Are we getting the most out of the UCAV concept?

- unmanned = loss of flexibility
 - mission planning restricted operational areas & times
 - autonomy dealing with the unexpected!
- so what are the advantages?
 - cost
 - expendability D³ missions
- but are these being achieved?
- UCAVs still designed as 'unmanned manned aircraft'
 - large, complex & expensive
 - long development times & protracted in-service life
 - definitely *not* expendable!



Instead, design for short service life ...

- accept the inevitability of high attrition rate in service
 - wooden round' concept unworkable
 - launch & recovery accidents etc
 - operating in harms way
- design for short term flexibility
 - high-cost systems transported in low-cost airframe
 - modular 'plug & play' architecture not integrated!
- plan for long term flexibility
 - rapid response to changes in concepts of use
 - take advantage of advances in airframe technology
- design for expendability
 - cost, numbers, replacement time
 - operators must be prepared to lose platforms



How are we going to do this?

- key factors
 - cost development & manufacture
 - development time
 - platform flexibility
- look for common element ...
 - → the flight control system
 - design
 - development
 - clearance
- what's the problem with current FCS design process?
 - linear process
 - protracted & costly!



Conventional linear FCS design process

- FCS designed & implemented before 1st flight
 - complex, highly integrated systems
 - financial & political implications of accidents in flight test
- FCS design largely simulation based
 - therefore needs high quality aerodynamic S&C model
- extensive platform characterisation required
 - 1000's of hours of wind tunnel testing
 - specialist test facility needs for S&C
- but FCS problems still common in early flight test
 - F-16, F-22, Gripen, Dark Star etc ...
- FCS development & clearance now the major element of a flight test programme



An alternative approach?

- do we really need a high level of integration?
 - are performance benefits worthwhile for low-cost UCAV?
- multiple losses in flight test acceptable for UCAVs
 - basic airframes are cheap, electronics are robust
- opportunities offered by modern FCS design tools
 - Nonlinear Dynamic Inversion (NDI)
 - full (or accurate!) aero model not required for basic control
 coupled with availability of
 - low-cost, high-performance computing hardware
 - improved data analysis techniques
 - low-cost, rapid airframe manufacturing methods
 - COTS airframe components

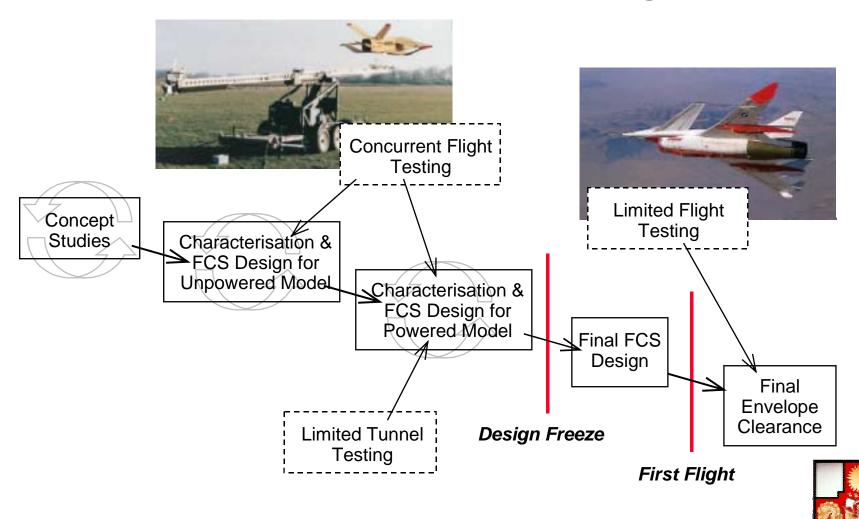


Iterative UCAV FCS development

- combine
 - aerodynamic characterisation
 - FCS design & development
 - platform optimisation
 - flight test
 - in a single integrated, iterative process
- aerodynamic model and flight control laws developed in *parallel*
 - NDI (or similar) coupled with advanced non-linear parameter ID
 - recast aero model in control system form eg aerodynamic transfer function
- final aero model 'only as good as it needs to be'



A possible iterative UCAV design process



Aspects of an iterative approach

- use industry-standard control system design tools
 - PC-based FCS maximum use of COTS components
 - desktop design & development environment
 - VAAC Harrier demonstrates potential of this approach
- an alternative 2-stage approach to clearance
 - control system architecture validated at sub-scale
 - verification of final (auto-coded) implementation
- flexible development process
 - technology insertion opportunities
- continuous risk reduction exercise
- shorter timescales & reduced cost
- "fit for purpose' FCS

